

USER'S OPERATING MANUAL FOR PID DIGITAL TEMPERATURE CONTROLLER

(Models : Px-414 / 714)



Px - 414
(48 X 48)



Px - 714
(72 X 72)

SPECIFICATIONS : -

1. **DISPLAY TYPE** : 4- Digit 7 segment LED (Bright)

Model No.	Px - 414	Px - 714
Display height (PV)	0.39"	0.59"

STATUS LED : OP 1 : Main Control Output

2. INPUT

Sensor input : TC: J,K,R,S,N,T,B & RTD: Pt-100
Range : Refer below table.

Sensor Type	Range	Resolution	Accuracy
Fe-k(J) T/C	0 ~ 760°C	1 °C	± 1 °C
Cr-AL(K) T/C	-99 ~ 1300°C	1 °C	
(R) T/C	0 ~ 1700°C	1 °C	
(S) T/C	0 ~ 1700°C	1 °C	
TC - N	-99 ~ 1300°C	1 °C	
TC - T	-99 ~ 400°C	1 °C	
TC - B	0 ~ 1800°C	1 °C	
Pt-100(RTD)	-100 ~ 450°C	1 °C	± 0.3 °C
Pt-100(RTD 0.1)	-99.9 ~ 450.0°C	0.1 °C	

Sampling Time : 125 msec.
Resolution : 1°C/0.1°C(Only for RTD)
CJC for TC : Built in automatic
LWC for Pt-100 : Built in upto 18E max.
Digital Filter : 1 to 10 Sec.

3. RELAY OUTPUT

Contact type : N/O, CM, N/C
Contact Rating : 5A @ 250VAC or 30 VDC
Life expectancy : > 5,00,000 operations
Isolation : Inherent

4. SSR DRIVE OUTPUT

Drive Capacity : 12V @ 30mA.
Isolation : Non-Isolated.

5. FUNCTION

Output 1 : Main Control output
Control Action : ON-OFF/PID (Select)
Control Mode : Heat/Cool (Select)

6. ENVIRONMENTAL

Operating Range : 0 ~50°C, 5~90% Rh
Storage Humidity : 95% Rh (Non-condensing)

7. POWER SUPPLY

Supply Voltage : 90~270VAC, 50/60Hz.
Consumption : 4W Maximum.

8. PHYSICAL

Housing : ABS Plastic

Model no.	Px-414	Px-714
Weight (gms.)	130	240

SAFETY INSTRUCTION : -

This controller is meant for temperature control applications. It is important to read the manual prior to installing or commissioning of controller. All safety related instruction appearing in this manual must be followed to ensure safety of the operating personnel as well as the instrument.

GENERAL : -

- ❖ The controller must be configured correctly for intended operation. Incorrect configuration could result in damage to the equipment or the process under control or it may lead personnel injury.
- ❖ The controller is generally part of control panel and in such a case the terminals should not remain accessible to the user after installation.

MECHANICAL : -

- ❖ The Controller in its installed state must not come in close proximity to any corrosive/combustible gases, caustic vapors, oils, steam or any other process by-products.
- ❖ The Controller in its installed state should not be exposed to carbon dust, salt air, direct sunlight or radiant heat.
- ❖ Ambient temperature and relative humidity surrounding the controller must not exceed the maximum specified limit for proper operation of the controller.
- ❖ The controller in its installed state must be protected against excessive electrostatic or electromagnetic interferences. Ventilation slits provided on the chassis of the instrument are meant for thermal dissipation hence should not be obstructed in the panel.

ELECTRICAL : -

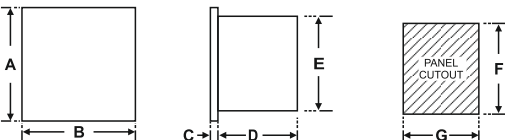
- ❖ The controller must be wired as per wiring diagram & it must comply with local electrical regulation.
- ❖ Care must be taken not to connect AC supplies to low voltage sensor input.
- ❖ Circuit breaker or mains s/w with fuse (275V/1A) must be installed between power supply and supply terminals to protect the controller from any possible damage due to high voltage surges of extended duration.
- ❖ Circuit breaker and appropriate fuses must be used for driving high voltage loads to protect the controller from any possible damage due to short circuit on loads.
- ❖ To minimize pickup of electrical noise, the wiring for low voltage DC and sensor input must be routed away from high current power cables. Where it is impractical to do this, use shielded ground at both ends.
- ❖ The controller should not be wired to a 3-Phase supply with unearthed star connection. Under fault condition such supply could rise above 264 VAC which will damage the controller.
- ❖ The Electrical noise generated by switching inductive loads might create momentary Fluctuation in display, alarm latch up, data loss or permanent damage to the instrument. To reduce this use snubber circuit across the load.
- ❖ It is essential to install a over Temp. Protection device to avoid any failure of heating system. Apart from spoiling the product, this could damage the process being controlled.

MECHANICAL INSTALLATION

The label on the controller identifies the serial number, wiring connections and batch number.

OVER ALL DIMENSIONS & PANEL CUT OUT (IN MM)

MODEL:-Px-414



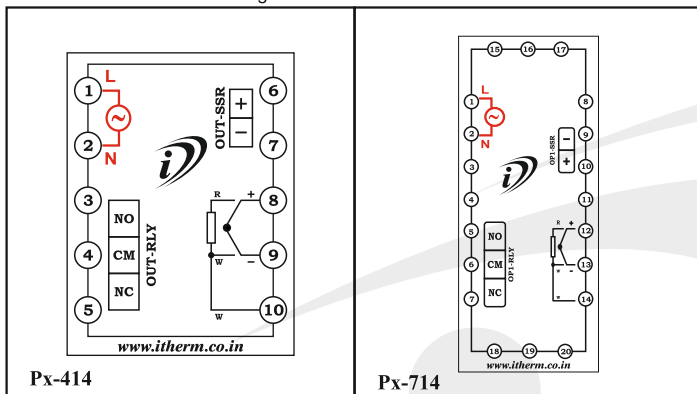
Dim Model	A	B	C	D	E	F	G
Px - 414	50	50	3	70	45	45	45
Px - 714	72	72	3	60	68	68	68

INSTALLATION GUIDELINES

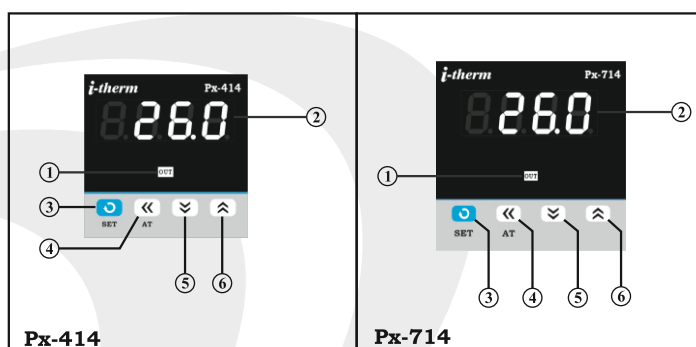
1. Prepare the cut-out with proper dimension as shown in figure.
2. Remove clamp from controller
3. Push the controller through panel cut-out and secure the controller in its place by tightening the side clamp.

ELECTRICAL INSTALLATION

The electrical connection diagram is shown on the controller enclosure as below.



FRONT PANEL LAYOUT



FRONT PANEL LAYOUT DESCRIPTION :

Sr.	NAME	FUNCTION
1	OP1 LED	Glows when OP1 is ON & flashes when delay time (dly1) is in operation(if selected mode is ON-OFF)
2	DISPLAY	It will display (1)Measured value of selected input or Error messages. (2) SP value in run mode. Parameters Values/code in program mode
3	SET KEY	(1) For SP programming. (2) To access Control mode. (3) To access Configuration mode along with UP key. (4) To scroll the parameter & to store its value.
4	SHIFT KEY	(1) To increase/alter parameter value in program mode with Up / Dn Key. (2) Press for 3Sec in Programming this will help to go back to previous parameter.
5	DOWN KEY	(1) To decrease / alter parameter value in program mode. (2) To enter in tune mode (with UP Key).
6	UP KEY	(1) To increase/alter parameter value in program mode. (2) To Enter in configuration mode (with SET key) . (3) To acknowledge Alarm. (4) To enter in tune mode (with DOWN Key).

PROGRAMMING :

USER LIST : To access the user list Press & Release SET key once.

(All following selected parameter's code shown in shaded will be displayed for 1 sec. followed by their values / options).

PARA METER	DISPLAY	RANGE	DESCRIPTION	DEFAULT
Control Set Point	SP > <input type="text" value="0"/>	LSPL ~ HSPL	User can change SP value using UP/ DOWN keys. Holding the key, will change the value at a faster rate. Press SET key to store the value & move on to the next parameter.	0°C

CONTROL LIST : To enter in this mode press SET & DOWN key simultaneously for 3 sec. User can set the control parameters.

(All following selected parameter's code shown in shaded will be displayed for 1 sec. followed by their values / options)

PARA METER	DISPLAY	RANGE	DESCRIPTION	DEFAULT
LOCK CODE	LOCK > <input type="text" value="0"/>	1 ~ 9999	Set this parameter to 15 (Default LOCK CODE) to access Control List. User has a choice to set different Lock Code via USER LOCK CODE in Config. List.	0
PRORTIONAL BAND	Pb > <input type="text" value="5.0"/>	0.5 to 99.9°C	This parameter will be prompted only if selected control action is PID. It sets bandwidth over which the output power is adjusted depending upon the error (SV-PV). The value of this parameter is automatically set by Auto tune function.	5.0°C

PARAMETER	DISPLAY	RANGE	DESCRIPTION	DEFAULT
INTEGRAL TIME	Int > 240	0 to 9999 Sec.	This parameter will be prompted only if selected control action is PID. It sets the time taken by PID algorithm to remove steady state error. Value of this parameter is automatically set by Auto Tune function. If set to '0', this function will be disabled.	240
DERIVATIVE TIME	dt > 60	0 to 300 Sec.	This parameter will be prompted only if selected control action is PID. It defines how strongly the Controller will react to the rate of change of PV. Value of this parameter is automatically set by Auto Tune function. If set to '0', this function will be disabled.	60
CYCLE TIME	CYCL > 16.0	0.5 to 100.0 Sec.	This parameter will be prompted only if selected control action is PID. User can set this value based on process being controlled & type of Output being selected. For Relay O/P, cycle time should be more than 12sec & for SSR O/P, cycle time should be less than 5 Sec.	16.0 Sec.
OUTPUT POWER LIMIT	OUTL > 100.0	0.0 % TO 100.0 %	This parameter will be prompted only if selected control action is PID. This parameter will decide the maximum output power in % applied to the load	100 %.
TUNE OFFSET	TOFS > 100	50 % to 100 %	This parameter will be prompted only if selected control action is PID. This parameter allows the user to carry out Auto Tuning function below the set point. (If tune offset is set to 50 %, tuning will be carried out at 50 % of the set point and if set to 100 %, tuning will be carried out at 100 % of the set point.)	100 %.
CONTROL HYS.	HYSL > 2	1 to 25 °C	This parameter will be prompted only if selected control action is ON-OFF. It sets the dead band between ON & OFF switching of the Output. Larger value of hysteresis minimize the number of ON-OFF operation of load. This increases life of actuators like contactors but also produces large errors (between PV & SV).	2°C
DELAY	dLY > 0	0 to 500 Sec.	This parameter will be prompted only if selected control action is ON-OFF. It sets the output restart time where O/P once turned OFF will turn ON only after restart time, regardless difference between PV & SP in Heat or Cool mode. If set to '0', O/P will be switched without delay. Also, Delay will be applicable at every power ON.	0 Sec.
OUTPUT OFF	OP.OF > d56L	1 to 10	This parameter will be prompted only if selected control action is PID. With this parameter O/P will be Completely OFF after the Set Point + Offset Value. If Disable, O/P will act Depending upon the PID Value after Set Point achieved.	Disable

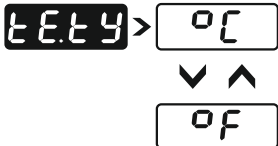




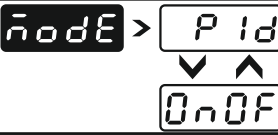
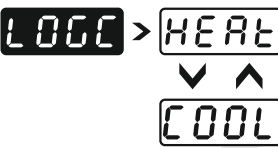
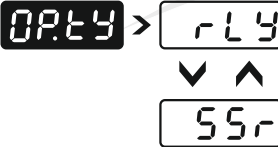

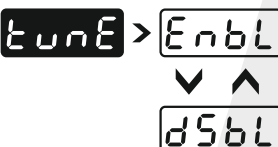
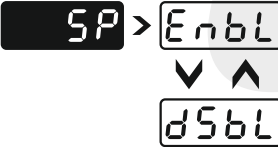

CONFIGURATION LIST : (1) To enter in this mode, press and hold SET & UP key simultaneously for 3 sec.

(2) Press UP or DOWN key to scroll between parameter options.

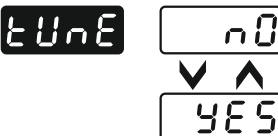
(3) Press SET key to store the current parameter & move on to the next parameter.

(All following selected parameter's code shown in shaded will be displayed for 1 sec. followed by their values / options)

PARAMETER	DISPLAY	DESCRIPTION	DEFAULT																																	
LOCK CODE	LOCK > 0	Set this parameter to 15 (Default LOCK CODE) to access Config. List. User has a choice to set different Lock Code between 1 to 9999 via USER LOCK CODE in Config. List.	0																																	
INPUT TYPE	INPT > TC-J ↓ ↑ TC-P ↓ ↑ TC-r ↓ ↑ TC-S ↓ ↑ TC-n ↓ ↑ TC-t ↓ ↑ TC-b ↓ ↑ rtd ↓ ↑ rtdi	<p>This parameter value is set according to the type of sensor (Thermocouple or RTD input) connected to the controller's input terminals.</p> <table border="1"> <thead> <tr> <th>Sensor Type</th> <th>Range</th> <th>Resolution</th> <th>Accuracy</th> </tr> </thead> <tbody> <tr> <td>Fe-k(J) T/C</td> <td>0 ~ 760°C</td> <td>1 °C</td> <td rowspan="10">± 1 °C</td> </tr> <tr> <td>Cr-AL(K) T/C</td> <td>-99 ~ 1300°C</td> <td>1 °C</td> </tr> <tr> <td>(R) T/C</td> <td>0 ~ 1700°C</td> <td>1 °C</td> </tr> <tr> <td>(S) T/C</td> <td>0 ~ 1700°C</td> <td>1 °C</td> </tr> <tr> <td>TC - N</td> <td>-99 ~ 1300°C</td> <td>1 °C</td> </tr> <tr> <td>TC - T</td> <td>-99 ~ 400°C</td> <td>1 °C</td> </tr> <tr> <td>TC - B</td> <td>0 ~ 1800°C</td> <td>1 °C</td> </tr> <tr> <td>Pt-100(RTD)</td> <td>-100 ~ 450°C</td> <td>1 °C</td> </tr> <tr> <td>Pt-100(RTD 0.1)</td> <td>-100.0 ~ 450.0°C</td> <td>0.1 °C</td> <td>± 0.3 °C</td> </tr> </tbody> </table>	Sensor Type	Range	Resolution	Accuracy	Fe-k(J) T/C	0 ~ 760°C	1 °C	± 1 °C	Cr-AL(K) T/C	-99 ~ 1300°C	1 °C	(R) T/C	0 ~ 1700°C	1 °C	(S) T/C	0 ~ 1700°C	1 °C	TC - N	-99 ~ 1300°C	1 °C	TC - T	-99 ~ 400°C	1 °C	TC - B	0 ~ 1800°C	1 °C	Pt-100(RTD)	-100 ~ 450°C	1 °C	Pt-100(RTD 0.1)	-100.0 ~ 450.0°C	0.1 °C	± 0.3 °C	TC - J
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TEMP TYPE		°C : If selected, the instrument will display the temperature in °C.	°C
		°F : If selected, the instrument will display the temperature in °F.	
LOWER SP LIMIT		Sets the minimum limit for set point adjustment. It can be set from minimum specified range of selected sensor to HSPL value.	0 °C
HIGHER SP LIMIT		Sets the maximum limit for set point adjustment. It can be set from LSPL value to maximum specified range of selected sensor.	400 °C
PROCESS VALUE OFFSET		Function of this parameter is to add/subtract a constant value to the measured PV to obtain Final PV for control applications. This parameter value needs to be altered for one of the following reason : - (i) To compensate for known thermal gradient (ii) To match the display values with another recorder or indicator measuring the same PV.	0 °C
INPUT FILTER		Controller is equipped with an adaptive digital filter which is used to filter out any extraneous pulses on the PV. Filtered PV Value is used for all PV dependent functions. If PV signal is fluctuating due to noise, increase the filter time constant value.	4
CONTROL MODE		User can select between PID or ON-OFF action algorithm to be adopted for output.	PID
CONTROL LOGIC		This parameter will be prompted only if selected control mode is ON-OFF. User can select HEAT logic in which OP1 will remain ON till PV < SP. (PV increases when output is ON.)	HEAT
		This parameter will be prompted only if selected control mode is ON-OFF. User can select cooling logic in which OP1 will remain ON till PV > SP. (PV decreases when output is ON.)	
OUTPUT TYPE		User has to set this parameter very carefully in accordance with the output used. (Separate terminal for RELAY & SSR : - Refer electrical installation) Select Relay if LOAD is connected via contactor. Whenever user selects Relay, Cycle time will automatically set to 16 sec. User can modify cycle time via Control List. Select SSR if LOAD is connected via SSR (DC voltage pulses). Whenever user selects SSR, Cycle time will automatically set to 1sec. User can modify cycle time via Control List.	RELAY
OVERSHOOT CONTROL POINT		This parameter will be prompted only if selected control action is PID. Setting this parameter on higher side will slows down the rate of rise of PV to minimize overshoot (this may cause delay to reach SP). Disabling or Setting this parametr on lower side will increase the rate of rise of PV (which may cause overshoot). Disable this option if delay is not required to reach SP. (This may cause overshoot w.r.t. SP)	DISABLE
AUTO TUNE		If Enabled, this parameter will be prompted if user press Up & Down keys Simultaneously for 3Sec.	ENABLE
		If Disabled, this parameter will not be prompted if user press Up & Down keys Simultaneously for 3Sec.	
SET POINT 1		If Enabled, User can View & edit the Set point 1 in USER list.	ENABLE
		If disabled, User can only View the Set Point 1 but Can not edit it in USER list.	
USER LOCK CODE		Default USER LOCK CODE is 15 to access Control & Configuration List. User has a choice to set its own USER LOCK CODE between 1 to 9999, this is to prevent unauthorized access of Control & Configuration List.	15

AUTO TUNING MODE : To enter in this mode, Press & hold SHIFT key for minimum 3 sec.

PARAMETER	DISPLAY	DESCRIPTION	DEFAULT
AUTO TUNING MODE		This function will be executed only if selected control action is PID. Auto-tuning function can be initiated by setting this parameter to 'YES'. The decimal of LSB flashes till Auto Tuning function is in progress. During Auto-tuning, Controller learns the process characteristics by itself & calculates required P, I & D values. User can cancel or abort this feature by setting this parameter to 'NO'.	NO



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